



Automated Discovery of Relationships, Models, and Principles in Ecology

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Ecological systems are the quintessential complex systems, involving numerous high-order interactions and non-linear relationships. The most used statistical modeling techniques can hardly accommodate the complexity of ecological patterns and processes. Finding hidden relationships in complex data is now possible using massive computational power, particularly by means of artificial intelligence and machine learning methods. Here we explored the potential of symbolic regression (SR), commonly used in other areas, in the field of ecology. Symbolic regression searches for both the formal structure of equations and the fitting parameters simultaneously, hence providing the required flexibility to characterize complex ecological systems. Although the method here presented is automated, it is part of a collaborative human-machine effort and we demonstrate ways to do it. First, we test the robustness of SR to extreme levels of noise when searching for the species-area relationship. Second, we demonstrate how SR can model species richness and spatial distributions. Third, we illustrate how SR can be used to find general models in ecology, namely new formulas for species richness estimators and the general dynamic model of oceanic island biogeography. We propose that evolving free-form equations purely from data, often without prior human inference or hypotheses, may represent a very powerful tool for ecologists and biogeographers to become aware of hidden relationships and suggest general theoretical models and principles.

Keywords: artificial intelligence, ecological complexity, evolutionary computation, genetic programming, species richness estimation, species-area relationship, species distribution modeling, symbolic regression

INTRODUCTION

Complexity is a term often used to characterize systems with numerous components interacting in ways such that their collective behavior is difficult to predict, but where emergent properties give rise to patterns, more or less simple but seldom linear (**Table 1**) (Holland, 1995; Mitchell, 2009). Complex systems science is therefore an effort to understand non-linear systems with multiple

TABLE 1 | Glossary of terms.

Artificial Intelligence (AI)—A scientific field concerned with the automation of activities we associate with human thinking (Russell et al., 2010).

Big data—Very large amount of structured or unstructured data, hard to model with general statistical techniques but with the potential to be mined for information.

Complex system—A system in which a large network of components organize, without any central controller and simple although non-linear rules of operation, into a complex collective behavior that creates patterns, uses information, and, in some cases, evolves, and learns (Mitchell, 2009).

General model—An equation that is found to be useful for multiple datasets, often but not necessarily, derived from a general principle. In most cases the formal structure of equations is kept fixed, while some parameters must be fitted for each individual dataset.

General principle—Refers to concepts or phenomenological descriptions of processes and interactions (Evans et al., 2013). May not have direct translation to any general model, but be a purely conceptual abstraction.

Genetic programming (GP)—A biologically-inspired method for getting computers to automatically create a computer program to solve a given problem (Koza, 1992). It is a type of evolutionary algorithm, where each solution to be tested (individual in a population of possible solutions) is a computer program.

Pareto front—A curve connecting a set of best solutions in a multi-objective optimization problem. If several conflicting objectives are sought (e.g., minimize both error and complexity of formulas), the Pareto front allows visualizing the set of best solutions (Smits and Kotanchek, 2005).

Symbolic regression (SR)—A function discovery approach for modeling of multivariate data. It is a special case of genetic programming, one where possible solutions are equations instead of computer programs.

connected components and how “the whole is more than the sum of the parts” (Holland, 1998). Biological systems probably are among the most complex (Solé and Goodwin, 2000), and among them, ecological systems are the quintessential complex systems (Anand et al., 2010). These are composed of individuals from different species, interacting and exchanging energy in multiple ways, furthermore, relating with the physical environment at different spatial and temporal scales in non-linear relationships. Consequently, ecology is dominated by idiosyncratic results, with most ecological processes being contingent on the spatial and temporal scales in which they operate. This makes it difficult to identify recurrent patterns, knowing also that pattern does not necessarily identify process (Lawton, 1996; Dodds, 2009; Passy, 2012). The most used exploratory (e.g., principal component analysis) and statistical modeling techniques (e.g., linear and non-linear regressions) can hardly reflect the complexity of ecological patterns and processes, often failing to find meaningful relationships in data. More flexible techniques, such as generalized additive models (GAMs), usually do not allow an easy interpretation of results and particularly of putative causal relationships (e.g., Sugihara et al., 2012). For ecological data, we require more flexible and robust, yet amenable to full interpretation, analytical methods, which can eventually lead to the discovery of general principles and models.

The aim of any ecological principle is to provide a robust model for exploring, describing, and predicting ecological

processes regardless of taxon identity and geographic region (Lawton, 1996; Dodds, 2009). Finding a recurrently high goodness-of-fit for a model to an ecological pattern for most taxa and ecosystems is usually a compelling evidence of a mechanistic process controlling that pattern. When general principles are translated into robust models, general statistical methods are mostly abandoned in favor of these, of which only few examples exist in ecology (**Data Sheet 1**). Such general, widely applicable equations are mostly found by intellectual *tour de force*. Yet, they are only the tip of the iceberg, usually incorporating few of the variables increasingly available to ecologists and that could potentially explain such patterns.

The automation of techniques for collecting and storing ecological and related data, with increasing spatial and temporal resolutions, has become one of the central themes in ecology and bioinformatics. Yet, automated and flexible ways to synthesize such complex and big data were mostly lacking until recently (Martin et al., 2018; Chen et al., 2019; Desjardins-Proulx et al., 2019). Finding hidden relations within such data is now possible using massive computational power. New computer-intensive methods have been developed or are now available or possible (Reshef et al., 2011), including the broad field of artificial intelligence (AI) or machine learning (ML) which have produced a variety of approaches (Lu, 2019). Artificial intelligence includes a series of evolution-inspired techniques, brought together in the sub-field of evolutionary computation, of which the most studied and well-known probably are genetic algorithms (Holland, 1975). Genetic programming, namely in the form of symbolic regression (SR) (Koza, 1992), is a derivation of genetic algorithms that searches the space of mathematical equations without any constraints on their form. Hence, it provides the required flexibility to represent complex systems as presented by many ecological systems (**Figure 1**). Contrarily to traditional statistical techniques, symbolic regression searches for both the formal structure of equations and the fitting parameters simultaneously (Schmidt and Lipson, 2009). Finding the structure of equations is especially useful to discover general models, providing insights into the processes and eventually leading to the discovery of new and yet undiscovered principles. Fitting the parameters provides insight into the raw data and allow for specific predictions. Successful examples on the use of SR in ecology include modeling of land-use change (Manson, 2005; Manson and Evans, 2007), effects of climate change on populations (Tung et al., 2009; Larsen et al., 2014), community distribution (Larsen et al., 2012; Yao et al., 2014), predicting micro-organismal blooms (Muttill and Lee, 2005; Muttill and Chau, 2006; Jagupilla et al., 2015; Tromas et al., 2017), deriving vegetation indices (Almeida et al., 2015), forecasting the trophic evolution of lakes (Bertoni et al., 2016), using parasites as biological tags (Barrett et al., 2005), and even to revisit classical ecological models such as the Lotka–Volterra predator–prey equation (Martin et al., 2018; Chen et al., 2019).

The goal of this work is to explain, test, and show the usefulness of SR in uncovering hidden relationships within typical ecological datasets. To illustrate this, we used five case studies reflecting typical analytical problems faced by ecologists. In the first example, (i) we test the robustness of SR when finding the power law applied to the species–area relationship (SAR) with

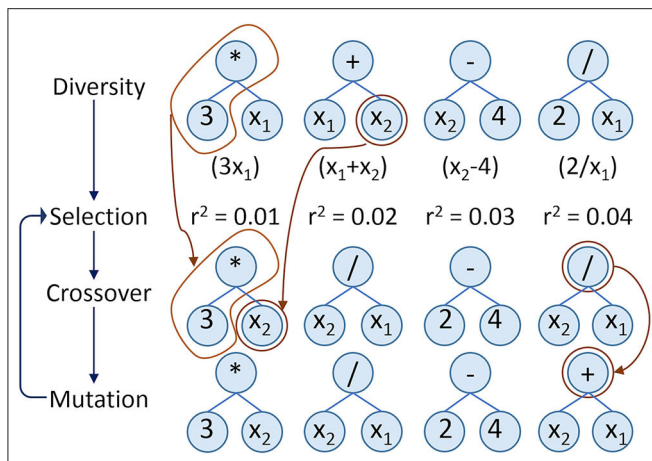


FIGURE 1 | Schematic representation of the symbolic regression workflow. The basic representation is a parse-tree where building blocks such as variables (in this case: x_1 , x_2), parameters (integers or real numbers), and operators (e.g., +, -, \times , \div) are connected forming functions (in parenthesis under the first line of trees). Initial equations are generated by randomly linking different building blocks. Equations are combined through crossover, giving rise to new equations with characteristics from both parents (arrows linking the first and second rows of trees). Equations with better fitness (e.g., R^2) have higher probabilities of recombining. To avoid loss of variability, a mutation step is added after crossover (arrows linking the second and third rows of trees). After multiple generations, evolution stops and a set of free-form equations best reflecting the input data is found.

extreme levels of noise, even beyond the high levels typical of ecological datasets. In the next two examples, we demonstrate how SR can deal with complex datasets, namely to model (ii) species richness; and (iii) species spatial distributions. Finally, we illustrate how SR can be used to find general models in ecology, by using it to develop new formulas for (iv) species richness estimation; and v) the general dynamic model of oceanic island biogeography (GDM).

GENERAL METHODOLOGY

Symbolic regression works as a computational parallel to the evolution of species. A population of initial equations is generated randomly by combining different building blocks, such as the variables of interest (independent explanatory variables), algebraic operators (e.g., +, -, \div , \times), analytic function types (exponential, log, power, etc.), constants and other ways to combine the data (e.g., Boolean or decision operators) (Figure 1). Being random, these initial equations almost invariably fail in describing the patterns or phenomena of interest, but some equations are slightly better than others. All are then combined through crossover, giving rise to new equations with characteristics from both parents. Equations with better fitness—as estimated using a chosen statistical measure such as R^2 or Akaike's Information Criterion (AIC; Akaike, 1974)—have a higher probability of recombining. To avoid new equations being bounded by initially selected building blocks or quickly losing variability along the evolutionary process, a mutation step (acting

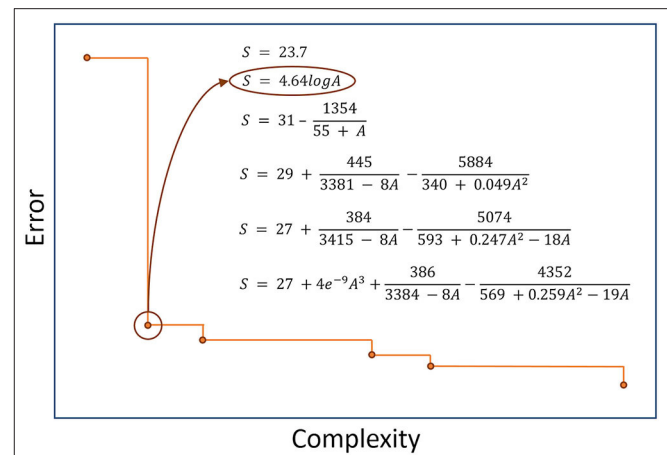


FIGURE 2 | Example of a Pareto front depicting error vs. complexity. This example reflects a symbolic regression search of the best species–area relationship for native spiders in the Azores (Portugal). The second formula is clearly the most promising, with both high accuracy (low error) and low complexity. In many occasions a single formula is not clearly best, in which case weights can be given to each of them through indices that simultaneously positively weight accuracy and negatively weight complexity (such as AIC or BIC) and/or multiple formulas presented as possible outcomes.

on any building block) is added to the process after crossover. After multiple generations, an acceptable level of accuracy by some of the equations is often attained and the researcher stops the process.

For this work we used the software Eureqa (Nuttonian, Inc) (Schmidt, 2015), which provides an intuitive interface suitable also for non-expert SR users (Dubčáková, 2011). Although a commercial version is available, we used the freely available test version for all analyses. For each run, the software outputs a list of equations along an error/complexity Pareto-front (Smits and Kotanchek, 2005), with the most accurate equation for each level of complexity being shown (Figure 2). For the SR search we used only algebraic and analytic operators (+, -, \div , \times , log, power) in all examples below, so that outputs could be most easily interpreted. The goodness-of-fit was evaluated using R^2 or AIC, depending on the question (see below). The Pareto-front often presents an “elbow,” where near-minimum error meets near-minimum complexity. The equation in this inflection is closer to the origin of both axes and is a good starting point for further investigation—if both axes are in comparable qualitative scales. Often, however, this inflection point is not obvious, and a single formula is not clearly best. In such cases, weights can be given to each of them through indices that positively weight accuracy and negatively weight complexity, such as AICc (Akaike, 1974). However, in all cases it is important to check all formulas along the Pareto-front. Often equations or models that make immediate sense to the specific question may not be detected by these automated methods.

Each of the five case studies was analyzed independently and using different approaches to test the performance of SR against other methods. We often opted to use fully independent datasets for three reasons. First, we were looking for general formulas,

which should be tested against fully independent data. Second, it was a much more powerful and convincing way to demonstrate the method than using subsets of the same data, which necessarily have some common ground that facilitates the job of any method. Third, our datasets, as typical for many in ecology, often had very few observations, making it hard to do sub-setting in few cases.

CASE-STUDIES

Finding the Species-Area Relationship (SAR) With Extreme Levels of Noise

Typical ecological datasets not only have few data points, but these are prone to varying levels of noise. Noise can be due to natural phenomena, such as spillover from neighboring regions, unpredictable weather events, etc., lack of the most appropriate data to model the phenomena, or simply errors in measuring or sampling. Testing any novel method to its robustness to different sources and levels of noise is therefore imperative.

One of the most studied examples of SARs is their application to island biogeography (ISAR). The shape of ISARs has been modeled by many functions, but three of the simplest seem to be preferred in most cases, the power, exponential, and linear models (Triantis et al., 2012) (**Data Sheet 1**). The power model in particular includes island area (A) and two fitting parameters, c (the intercept) and z (the scaling of richness with area) (**Data Sheet 1**). Here we created 30 fictional islands each one corresponding to one of the 30 possible combinations resulting from five different areas (10, 100, 1000, 10,000, and 100,000 km²), two typical values for c (1 and 10), and three typical values for z (0.2, 0.3, and 0.4). We then simulated sampling from these 30 islands, each with a sampled richness equal to the multiplication of the true richness value by five different levels of noise as given by the standard deviation of a sampling from a normal distribution with mean = 1 and sd = 0, 0.1, 0.2, 0.4, and 0.8. The theoretical richness of each island was then multiplied by 10 simulations of each noise level using this approach, providing a total of 50 search trials (**Data Sheet 2**). We must emphasize that with sd = 0.8 the noise was extreme and unreasonable, with for example islands predicted to have 100 species presenting anything between 0 and 199 species after noise was added. We evaluated the ability of SR to develop the power law by counting at each noise level how many times the usual formulation and a derivation without the intercept c were found among the 10 searches per level.

Our simulations using SR were able to find the power-law of the SAR even with the most extreme scenarios (**Data Sheet 2**). From 100% success rate with sd = 0 or 0.1, to 70% with sd = 0.2, 50% with sd = 0.4, and 40% with sd = 0.8. If we include the simpler formulation with no intercept, success rate was 100, 100, 100, 90, and 80%, respectively for sd = 0, 0.1, 0.2, 0.4, and 0.8.

Modeling Species Richness

Modeling and mapping the species richness of high diversity taxa at regional to large scales is often impossible without extrapolation from sampled to non-sampled sites. Here, we used an endemic arthropod dataset collected in Terceira Island, Azores. Fifty-two sites were sampled using pitfall traps for

epigeal arthropods (Cardoso et al., 2009), 13 in each of four land-use types: natural forest, exotic forest, semi-natural pasture, and intensively managed pasture. In this problem, given the size of the dataset, we used a 5-fold cross validation. We explained and predicted species richness per site using elevation, slope, annual average temperature, annual precipitation, and an index of disturbance with values ranging from 0 (absence of human presence) to 100 (dense urban environment) (Cardoso et al., 2013). For SR we ran each fold five times to minimize the risk that the formulas found represented local optima. We then reported the average and range of R^2 and AICc of the five partitions for both the training and test data.

As the response variable was count data, Generalized Linear Models (GLM) and Generalized Additive Models (GAM) with a Poisson error structure and a log link were used. We used the package MuMIn (Barton, 2015) and the R environment (R Core Team, 2015) for multi-model inference based on AICc (Hurvich and Tsai, 1989) values, using all variables plus all possible interactions for GLM. For fitting GAM, we used package gam (Hastie, 2015). The R^2 goodness of fit was used as the fitness measure. For each run of the SR (25 in total) we picked the formula at the inflection point of the Pareto-front (**Data Sheet 2**). Both R^2 and AICc were used to compare GLM and GAM with SR on the test datasets.

The model selected by GLM in all five k -folds was:

$$S = e^{(a+bH - cP - dD)}$$

where H = altitude, P = precipitation, D = disturbance; a , b , c , and d are fitting parameters with mean $a = 1.894$ (range: 1.116–2.577), mean $b = 0.00419$ (range: 0.00360–0.00574), mean $c = 0.000972$ (range: 0.000726–0.001212), and mean $d = 0.0251$ (range: 0.0118–0.0331). The mean training $R^2 = 0.529$ (range: 0.469–0.573) and mean training AICc = 104.151 (range: 103.055–105.634). The mean testing $R^2 = 0.528$ (range: 0.313–0.770) and mean testing AICc = 45.340 (range: 41.913–48.513).

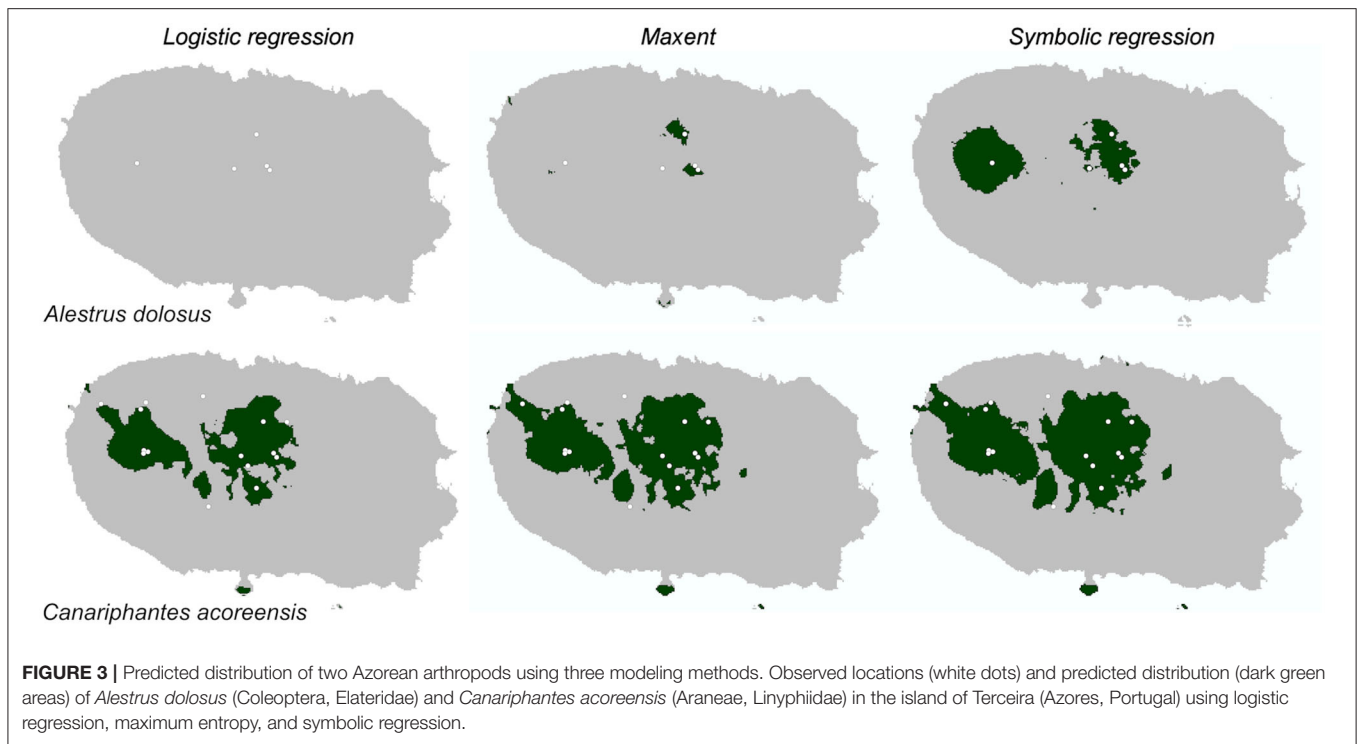
The results of GAM were similar to the GLM, the algorithm selecting the most parsimonious formulation equivalent to a GLM. The SR results performed considerably better than GLM or GAM with a much simpler formula using a single variable (Disturbance) and much better training and testing results, with 23 out of 25 formulas chosen being in the form:

$$S = (a/D) - b$$

where a and b were fitting parameters with mean $a = 140.787$ (range: 134.700–145.775) and mean $b = 1.325$ (range: 1.078–1.483). The mean training $R^2 = 0.603$ (range: 0.576–0.644) and mean training AICc = 52.631 (range: 47.982–56.985). The mean testing $R^2 = 0.601$ (range: 0.449–0.737) and mean testing AICc = 19.088 (range: 13.042–23.432). We should emphasize the simplicity of interpretation of this formula, indicating that species richness essentially was inversely related with disturbance.

Modeling Species Distributions

Species distribution modeling (SDM) is one of the most widely used correlative statistical approaches to biodiversity assessment,



for example to fill gaps in our knowledge on individual species distributions, predict species response to climate change, and the spread of invasive species (Araújo et al., 2019). As a case study, we modeled the potential distribution of two endemic Azorean species in Terceira Island: the rare forest click-beetle *Alestrus dolosus* (Crotch) (Coleoptera, Elateridae) and the abundant but mostly forest-restricted spider *Canariphantes acoreensis* (Wunderlich) (Araneae, Linyphiidae). We compared the performance of logistic regressions (GLM with a binomial error structure) and maximum entropy models (Maxent; Phillips et al., 2006) in predicting the distribution of the two species, to that of SR. GLM and MaxEnt are two of the most widely used approaches for SDM (Elith et al., 2006). Given the intrinsic differences between methods, we had to use different background datasets (Data Sheet 3). Maxent used the environmental maps of the islands with a resolution of 100 m, from where it extracted pseudo-absences. We then converted the probabilistic potential distribution maps to presence/absence using the maximum value of training sensitivity plus specificity as the threshold as recommended by Liu et al. (2005). Logistic regression and SR used presence/absence data from the 52 sampled sites. We conducted multi-model inference of logistic regression based on AICc values. In the SR run we included a step function, so that positive and negative values were converted to presence and absence (binary output), respectively. Absolute error, reflecting the number of incorrect classifications, was used as the fitness measure. As inflection points of the Pareto fronts were clear, the best SR formula for each species was chosen based on them (Data Sheet 2). Given the scarcity of occurrences of species in the dataset (from 10 to 35% of the data points) we opted

for a balanced split of 50% for training and test sets. In all cases only the training data (26 sites) were used to obtain the models. Logistic GLM, Maxent, and SR were compared in their performance for predicting presence and absence of species on the 26 test sites using the Sensitivity, Specificity, and True Skill Statistic (TSS) (Allouche et al., 2006).

The potential distribution models were relatively similar for *C. acoreensis* but show marked differences for *A. dolosus* (Figure 3). Symbolic regression outperformed both other models for *A. dolosus* and was as good as Maxent for *C. acoreensis*, with both outperforming logistic regression (Table 2). The SR models were not only the best, presenting maximum values for TSS, but were also the easiest to interpret. *A. dolosus* was predicted to have adequate environmental conditions in all areas above 614 m elevation, being restricted to pristine native forest. *Canariphantes acoreensis* could potentially be present in all areas with disturbance values below 41.3, occurring not only in native forest but also in adjacent semi-natural grassland and humid exotic forest. The logistic regression and Maxent models used a large number of explanatory variables for *A. dolosus* yet performed worse on the test data than did SR (Table 2).

Developing Species Richness Estimators

Several asymptotic functions have been used to estimate species richness (Soberón and Llorente, 1993), including the Clench function (Clench, 1979), the negative exponential function, and the rational function (Ratkowsky, 1990) (Data Sheet 1). We used SR to rediscover or eventually find novel asymptotic models that would outperform them. Two independent datasets were used resulting from exhaustive and standardized sampling for

TABLE 2 | Species distribution models for two endemic arthropod species on the island of Terceira (Azores, Portugal).

Model	Formula	Sensitivity	Specificity	TSS
<i>Alestrus dolosus</i>				
Logistic regression	$1/(1 + e^{-8469+0.432P+540.7T})$	0	1	0
Maxent	Uses all variables but <i>SI</i> , main is <i>D</i> (contribution = 74.1%)	0.5	1	0.5
Symbolic regression	<i>step</i> ($H-614$)	1	0.75	0.75
<i>Canariphantes açorensis</i>				
Logistic regression	$1/(1 + e^{-3.617+0.103D})$	0.667	0.7	0.367
Maxent	Uses only <i>D</i> (contribution = 100%)	0.833	0.65	0.483
Symbolic regression	<i>step</i> ($41.3-D$)	0.833	0.65	0.483

Accuracy statistics on an independent test dataset are given by the True Skill Statistic (TSS). *H* = altitude, *SI* = slope, *T* = average annual temperature, *P* = annual precipitation, and *D* = disturbance index. The *step* function in symbolic regression converts positive values inside parentheses to presence and negative values to absence. Best values in bold.

spiders in 1 ha plots, performed by 8 collectors during 320 h of sampling in a single hectare using five different methods (so-called sampling protocol “COBRA” —Conservation Oriented Biodiversity Rapid Assessment; Cardoso, 2009). The training dataset was from a mixed forest in Gerês (northern Portugal) and the test dataset was from a *Quercus* forest in Arrábida (southern Portugal) (Cardoso et al., 2008a,b).

Randomized accumulation curves for both sites were produced using the R package BAT (Cardoso et al., 2015). The true diversity of each site was calculated as the average between different non-parametric estimators (Chao 1 and 2, Jackknife 1 and 2). Because the sampled diversity in the training dataset reached a very high completeness but we wanted to simulate typically very incomplete sampling, datasets with 10, 20, 40, 80, and 160 randomly chosen samples were extracted and used, in addition to the complete 320 samples dataset, as independent runs in SR. Squared error was used as the fitness measure. Additionally, we imposed a strong penalty to non-asymptotic functions, although these were still allowed in the search process (see **Data Sheet 2** for details). The weighted and non-weighted scaled mean squared errors implemented in BAT (Cardoso et al., 2015) were used as accuracy measures.

For the training dataset, one asymptotic model was found by SR (**Data Sheet 2**):

$$S = \frac{aQ}{b + Q}$$

where *a* and *b* were fitting parameters. This model was in fact the Clench model with a different formulation (**Data Sheet 1**), where the asymptote was *a*. A second, slightly more complex but better fitting, model was found for partial datasets with 40 or more samples:

$$S = \frac{c + aQ}{b + Q}$$

where *c* is a third fitting parameter. The asymptote was again given by the value of *a* (**Figure 4**). This model was similar to the rational function (**Data Sheet 1**). It was found to outperform the Clench and negative exponential for both the training and testing datasets (**Table 3**).

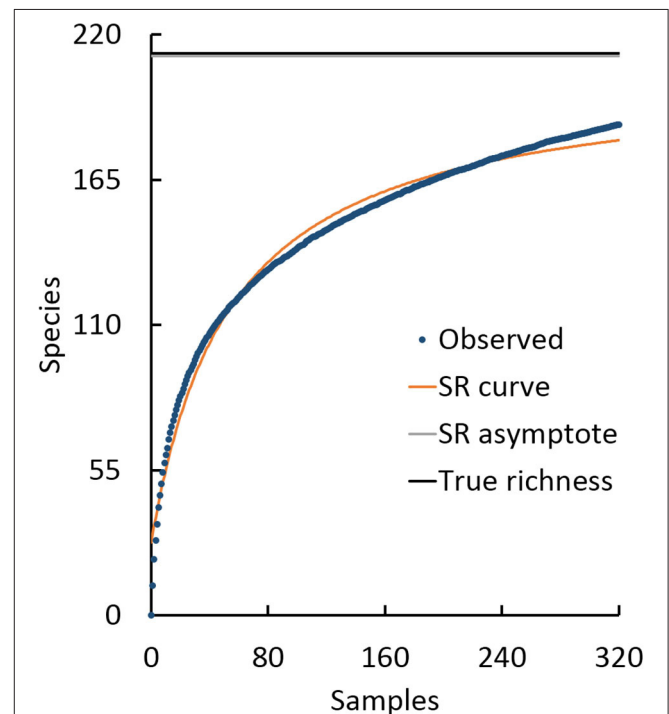


FIGURE 4 | Accumulation curve for spider sampling in Gerês (Portugal). The result of searching for the best fitting asymptotic formula using symbolic regression is also shown.

Developing the General Dynamic Model of Oceanic Island Biogeography (GDM)

The general dynamic model of oceanic island biogeography (GDM) was proposed to predict the responses of the key processes of immigration, speciation and extinction in volcanic islands, recognizing the role of geological processes in driving diversity on oceanic islands (Whittaker et al., 2008). Traditionally, the GDM is tested using a model where island species diversity is regressed as a function of area and age. Several different equations have been found to describe the GDM, extending the different SAR models with the addition

TABLE 3 | Comparison of three asymptotic equations used to estimate spider species richness in two forest sites.

Model	Raw accuracy	Weighted accuracy
Gerês (training)		
Observed	0.113	0.037
Clench	0.055	0.018
Negative exponential	0.115	0.049
Rational function	0.045	0.012
Arrábida (testing)		
Observed	0.103	0.031
Clench	0.038	0.010
Negative exponential	0.092	0.037
Rational function	0.032	0.008

See **Data Sheet 1** for formulas. Raw accuracy is the scaled mean squared error considering the entire observed accumulation curve (each formula was fitted to the curves using 4–320 samples) and weighted accuracy is this value weighted by the sampling effort at each point in the curve (where effort is the ratio between number of individuals and observed species richness). Note that lower values (in bold) are better as they reflect the deviation from a perfect estimator.

of a polynomial term using island age and its square (TT2), depicting the island's ontogeny. The first to be proposed was an extension of the exponential model (Whittaker et al., 2008), the power model extensions following shortly after (Fattorini, 2009; Steinbauer et al., 2013).

Our objective was to test if we could re-discover or eventually refine existing models for the ISAR and GDM from data alone. We used the Azores and Canary Islands spiders (Cardoso et al., 2010) as training data. To independently test the generality of models arising from spider data, we used bryophyte data from the same archipelagos (Aranda et al., 2014). The area and maximum time since emergence of each island were used as explanatory variables and the native species richness per island as the response variables (**Data Sheet 4**). The R^2 value was used as the fitness measure. The best SAR and GDM equations found by SR were chosen based on the inspection of the Pareto front (**Data Sheet 2**) but looking also for interpretability of the models. These were then compared with the existing models using AICc and the R package BAT (Cardoso et al., 2015).

For the Azorean spiders, the best fitting previous model (both highest R^2 and lowest AICc) for the ISAR was the exponential model (**Table 4**). The SR run discovered roughly the same model, indicating, however, that the intercept (c term) was adding unnecessary complexity. A similar ranking of models was verified for bryophytes in the same region, revealing the robustness of the new model.

For the Canary Islands, the best model for spiders was a linear function of area:

$$S = 75 + 0.047A$$

($R^2 = 0.364$, AICc = 65.631). Although it was easy to interpret, the explained variance was relatively low. The SR run reached a much higher explanatory power:

$$S = 112 - 1.002^A$$

($R^2 = 0.806$, AICc = 57.320). In this case though, the equation was over-fitting to the few available data (7 data points), as this function was erratic creating a biologically indefensible model. The reason the ISAR was hard to model for the Canary Islands spiders was because we were missing the major component Time (Cardoso et al., 2010). This was depicted by the GDM, of which the best of the current equations was found to be the power model described by Fattorini (2009) (**Table 4**). Nevertheless, using SR we were able to find an improved, yet undescribed, model (**Table 4**). This represented a general model expanding the linear SAR:

$$S = c + zA + XT - yT^2$$

When tested with Canarian bryophytes, this new formulation was almost as good as the power model (**Table 4**).

DISCUSSION

Symbolic regression has the advantage over most standard regression methods (e.g., GLM) of being more flexible, allowing a good fitting to data with better interpretability, since results are in the form of mathematical formulas. GLMs and other similar techniques assume linear relations between variables or require a priori knowledge on the form of the relation (e.g., quadratic, cubic, interactions between variables, etc.).

SR also has one or more advantages over other, commonly used, highly flexible regression (e.g., GAMs) or machine learning techniques (e.g., neural-networks): (1) numerical, ordinal, and categorical variables are easily combined; (2) redundant variables are usually eliminated in the search process and only the most important are retained if anti-bloat measures (intended to reduce the complexity of equations) are used. Incidentally, this also releases the user from the problem of dealing with collinearity (Dormann et al., 2013); (3) the evolved equations are human-readable and interpretable; and (4) solutions are easily applied to new data.

Using SR, we were able to “distill” free-form equations and models that not only consistently outperform but are more intelligible than the ones resulting from rigid methods, such as GLM, or “black-boxes,” such as Maxent. This was the case for both species richness and distribution models.

We were also able to re-discover and refine equations for estimating species richness based on sampling curves and the ISAR and GDM from data alone. All the examples presented in this work suggest that evolving free-form equations purely from data, often without prior human inference or hypotheses, may represent an under-explored but very powerful tool for ecologists and biogeographers, allowing the finding of hidden relationships in data and suggesting new ideas to formulate general theoretical principles.

The idea that SR is a powerful tool for reverse-engineering ecological theory from data is not new. Many examples reviewed in the introduction suggest that different authors across disparate disciplines understand this date back to the early 2000s. Recently, the potential of SR in ecology was discussed in two essays that showed how SR can be used to develop classic demographic time

TABLE 4 | Species area relationship (SAR) models for Azorean taxa and General Dynamic Models (GDM) of oceanic island biogeography for Canarian taxa.

Model	Formula	R ²	AICc
SAR Azorean Spiders (training)			
Power	$S = 13.379A^{0.438}$	0.642	32.505
Exponential	$S = 0.549 + 4.538 \log A$	0.780	28.102
Linear	$S = 19.357 + 0.017A$	0.435	36.604
SR	$S = 4.641 \log A$	0.780	23.319
SAR Azorean Bryophytes (testing)			
Power	$S = 181.625A^{0.803}$	0.666	78.085
Exponential	$S = -27.824 + 57.114 \log A$	0.728	76.208
Linear	$S = 196.215 + 0.259A$	0.617	79.295
SR	$S = 51.889 \log A$	0.722	71.617
GDM Canarian Spiders (training)			
Whittaker	$S = -185.589 + 41.732 \log A + 17.776T - 1.022T^2$	0.873	110.350
Fattorini	$\log S = 2.585 + 0.281 \log A + 0.157T - 0.009T^2$	0.941	105.025
Steinbauer	$\log S = 3.367 + 0.098 \log A + 1.502 \log T - 0.454 \log T^2$	0.814	113.007
SR	$S = 42.283 + 0.051A + 17.379T - T^2$	0.952	61.505
GDM Canarian Bryophytes (testing)			
Whittaker	$S = -176.599 + 66.602 \log A + 21.361T - 1.620T^2$	0.773	125.214
Fattorini	$\log S = 4.544 + 0.137 \log A + 0.126T - 0.009T^2$	0.803	124.217
Steinbauer	$\log S = 5.136 + 0.017 \log A + 1.063 \log T - 0.382 \log T^2$	0.612	128.963
SR	$S = 192.660 + 0.075A + 20.702T - 1.576T^2$	0.785	124.841

S = native species richness; A = area of the island; T = maximum time of emergence. Best models are indicated in bold.

series from data (Martin et al., 2018; Chen et al., 2019). Yet, our study is the first to bring together all these disparate applications, demonstrating the versatility of this tool by applying it to a range of diverse ecological and evolutionary problems, both theoretical and practical. These results suggest that the true potential for the use of SR in ecology and evolution is yet to be fulfilled.

From Particular to General Principles

Scientific fields such as physics rarely rely on general statistical inference methods such as linear regression for hypothesis testing. The complexity of ecology made such methods an imperative in most cases. Symbolic regression not only allows the discovery of relationships specific to particular datasets, but also the finding of general models, globally applicable to multiple systems of particular nature, as we tried to exemplify. SR has the significant advantage of generating a variety of expressions from the given function set. For example, other methods may be configured to fit a polynomial to the data, but the user has to specify the degree. In SR, the power function in addition to the four basic arithmetic operations, allows the generation of unlimited degree polynomials, therefore providing a wider exploration of the solution space.

As mentioned, SR is designed to optimize both the form of the equations and the fitting parameters simultaneously. The fitting parameters usually are specific to each dataset, but the form may give clues toward general principles. For example, all archipelagos will follow an ISAR, even if each archipelago will have its own c and z values. Although this aspect has not been explored in this study, we suggest two ways of finding general principles. First, as was hinted by our estimators' example, one

may independently analyse multiple datasets from the same type of systems. From each dataset, one or multiple equations may arise. Many of these will be similar in form even if the fitting parameters are different. Terms repeated in several equations along the Pareto front or with different datasets tend to be meaningful (Schmidt and Lipson, 2009). We may then try to fit the most promising forms to all datasets optimizing the fitting parameters to each dataset and look for which forms seem to have general value over all data. Second, one may simultaneously analyse multiple datasets from the same type of systems but with a change to the general SR implementation. Instead of optimizing both form and fitting parameters, the algorithm may focus on finding the best form, with fitting parameters being optimized during the evaluation step of the evolution for each dataset independently. This parameter optimization could be done with standard methods such as quasi-newton or simplex (Nocedal and Wright, 1999). To our knowledge, this approach has yet to be implemented, but it would allow finding general models and possibly principles, independently of the idiosyncrasies of each dataset.

The Need for Human Inference

Many data mining techniques are regarded, and rightly so, as "black boxes." SR is transparent in this regard, as variables are related through human-interpretable formulas. This is particularly important if the goal is to find equations with both predictive and explanatory power, building the bridge between finding the pattern and explaining the driving process, or if a general principle is to be suggested.

Our results show that an automated discovery system can identify meaningful relationships in ecological data. Yet, as shown by our Canary Island spider SAR model, some equations might be very accurate but overfit the data. As with any relationship finding, either automated or human, correlation does not imply causation, and spurious relationships are not only possible but probable given complex enough data.

Although the method here presented is automated, it is part of a collaborative human–machine effort. The possibility of exploiting artificial intelligence working together with human expertise can be traced back to Engelbart (1962), where the term “augmented intelligence” was coined to designate such collaboration. It has been subsequently developed and extended to teamwork involving one or more artificial intelligence agents together with one or (many) more humans, in diverse domains such as robotic teams (Yanco et al., 2004) or collective intelligence for evolutionary multi-objective optimization (Cinalli et al., 2015). In ecological problems, human knowledge may play a fundamental role: (1) in the beginning of the process, when selecting input variables, building blocks and SR parameters; and (2) in the interpretation and validation of equations. The choice of equations along a machine-generated Pareto front should also take advantage of human expert knowledge to identify the most interesting models to explain the data. The researcher might then decide to disregard, accept, or check equation validity using other methods.

A priori Knowledge

To some extent, it is possible to select a priori the type of models the algorithm will search for by selecting the functions to include in the function set. The choice of the function set is very important. A function set lacking a relevant function for the model may delay evolution or prevent it from finding a proper solution altogether. A way to take advantage of human expert knowledge is to seed the initial population of expressions with some we know are related with the problem. For example, when searching for the GDM we could have given the algorithm multiple forms of the ISAR to seed the search process. This is a directive approach and must be done in a parsimonious way, to avoid directing evolution too strongly, possibly trapping it in a local minimum. Such an approach should be complemented with random expressions in the initial population to create the necessary pool material for evolution to well explore the solution space. Therefore, a priori knowledge in SR has a stronger influence than in other inference methods, such as Bayesian, where a less adequate prior may be overcome by enough data.

Fine-Tuning the Process

The number of options in SR is immense. Population size is positively correlated with variability of models and how well the search space is explored, but might considerably slow the search. Mutation rates are also positively correlated with variability, but rates that are too high might prevent the algorithm converging on the best models. The fitness measure depends on the specific problem and on the type of noise in the data.

The number of generations to let the search run is entirely dependent on the problem complexity and time available. Often the algorithm reaches some equation that makes immediate sense to the researcher and the process can be immediately stopped for further analysis of results. Sometimes several competing equations seem to make sense but are not entirely convincing, in which case some indicators can be used as a stop rule, such as high values of stability and maturity of the evolution process (Schmidt, 2015).

The speed with which evolution occurs is extremely variable, depending on factors including the complexity of the relationships, having the appropriate variables and building blocks and the level of noise in the data. Fortunately, the process is easily adaptable to parallel computing, as many candidate functions can be evaluated simultaneously, allowing the use of multiple cores and even computer clusters to speed the search of equations.

Caveats

The SR approach is fully data-driven. This means it requires high-quality data if meaningful relationships are to be found. Also, it makes no a priori assumptions, so the final result might make no (obvious) sense, leading to spurious inferences, particularly if data are scarce or poor-quality, or if the right building blocks are not provided. Additionally, SR suffers from the same limitations of evolutionary algorithms in general. In many cases the algorithm may get stuck in local minima of the search space, requiring time (or even a restart with different parameters) to find the global minimum. Finally, SR suffers from the problem of bloat, which consists on an excessive growth of the expressions. There are mitigating approaches, like introducing a penalty for long expressions in the fitness function, or doing a posteriori symbolic analysis and simplification. However, bloat is still a problem under research.

Nevertheless, the fact that SR produces human legible expressions turns out to be useful even in the case of very large expressions. The expert eye can usually distinguish relevant fragments from a variety of unmeaningful segments of long expressions. And those relevant fragments often spur new thoughts and experiments.

The Automation of Science?

The methods here presented can be powerful additions to theoretical and experimental ecology, even if new conceptual hypotheses have to be created to accommodate the new equations. Such models could even be the only available means of investigating complex ecological systems when experiments are not feasible or datasets get too big/complex to model, using traditional statistical techniques (e.g., Tromas et al., 2017).

This family of techniques has led several authors to suggest the “automation of science” (King et al., 2009), where computers are able to advance hypotheses, test them, and reach conclusions in largely unassisted processes. This falls into the realm of exploiting knowledge (or symbolic)

driven AI together with data driven AI, or also automated machine learning an approach that recently began to gain momentum (e.g., Zhuang et al., 2017). SR potential is high in this automated science avenue since it bridges well from data to symbolic representations. What is clear already is its capability of producing formulas that help researchers to focus on initially imperceptible but interesting relationships within datasets and therefore SR may guide the process of hypothesis creation.

DATA AVAILABILITY STATEMENT

Eureqa scripts and Pareto front are available in **Data Sheet 2**. Data for Case study Modeling species richness are in Cardoso et al. (2013). Train and test datasets used for species distribution modeling are in **Data Sheet 3**. Dataset used in the case study Developing species richness estimators are available in the R package BAT (Cardoso et al., 2015). Dataset used in case study Developing the general dynamic model of oceanic island biogeography (GDM) are derived from Aranda et al. (2014) and Cardoso et al. (2010) see **Data Sheet 4**.

AUTHOR CONTRIBUTIONS

PC conceived the original idea and led the writing of the manuscript with LC. PC and VB performed the analyses with contributions from LC, JCC, and FR. PB and RG contributed with data. All authors contributed to the writing of the manuscript.

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SUPPLEMENTARY MATERIAL

The Supplementary Material for this article can be found online at: <https://www.frontiersin.org/articles/10.3389/fevo.2020.530135/full#supplementary-material>

Data Sheet 1 | Examples of general principles in ecology and of some of the respective statistical models.

Data Sheet 2 | Data and settings used for all Symbolic Regression analyses in the paper (Eureqa file: <http://www.nutonian.com/products/eureqa/>).

Data Sheet 3 | Train and test databases used for species distribution modeling.

Data Sheet 4 | Species, area, and age for each Canarian Island.

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Conflict of Interest: The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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